

ON THE CONDITIONS FOR A STABLE PROJECTION METHOD ON COLLOCATED UNSTRUCTURED GRIDS

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Most popular CFD codes like OpenFOAM or ANSYS-FLUENT use finite-volume discretizations on collocated unstructured meshes. While these discretizations are preferred over staggered ones for their simplicity, some errors may arise due to this approach, such as the checkerboard problem. A possible solution to this problem would be using a compact Laplacian operator \mathbf{L} instead of a wide-stencil Laplacian operator \mathbf{L}_c . However, even for symmetry-preserving discretizations [1], this approach may lead to instabilities for highly distorted meshes due to the (artificial) kinetic energy added, which is given by:

$$\mathbf{p}_c^T (\mathbf{M}\tilde{\mathbf{A}}^{-1}\mathbf{G} - \mathbf{M}_c\mathbf{A}^{-1}\mathbf{G}_c)\mathbf{p}_c = \mathbf{p}_c^T (\mathbf{L} - \mathbf{L}_c)\mathbf{p}_c, \quad (1)$$

where $\mathbf{A} = I_3 \otimes \mathbf{A}_c$, $\tilde{\mathbf{A}}^{-1} = \text{diag}(\Pi_{c \rightarrow s} \text{vec}(\mathbf{A}_c^{-1}))$, and $\Pi_{c \rightarrow s}$ is the scalar cell-to-face interpolator. The necessary and sufficient conditions, for explicit ($\mathbf{A}_c = Id$) or implicit time integration (\mathbf{A}_c diagonal with positive entries), to remove these instabilities by maintaining $\mathbf{L} - \mathbf{L}_c$ small and semi-negative definite are summarized in the following theorem:

Theorem Assume our projection method preserves the symmetry of the differential operators and ends up with a velocity correction that adds a kinetic energy error of the form $\mathbf{p}_c^T (\mathbf{L} - \mathbf{L}_c)\mathbf{p}_c$ (such as the Fractional Step Method or PISO); then, this contribution is negative if and only if the volume-weighted cell-to-face interpolator is used and these two geometrical conditions are satisfied by the mesh:

- 1. $V_k = \sum_f \tilde{V}_{k,f} n_{i,f}^2, \forall k \in \{1, \dots, n\}, i \in \{x, y, z\}$,
- 2. $\sum_f \tilde{V}_{k,f} n_{i,f} n_{j,f} = 0, \forall k \in \{1, \dots, n\}, i, j \in \{x, y, z\}, i \neq j$.

where $\tilde{V}_{k,f}$ is the quantity of staggered volume associated to control volume k , and $n_{i,f}$ are the components of the face-normal vector. This imposes geometrical constraints in the mesh that will be discussed during the conference.

REFERENCES

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