# On a Conservative Solution to Checkerboarding: Examining the Causes of Non-physical Pressure Modes

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# Origins of checkerboarding

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# Decoupling of pressure

- Collocated grid arrangement
- Central differencing discretisation
- Wide-stencil gradient, divergence & Laplacian



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# Decoupling of pressure

- Collocated grid arrangement
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#### Decoupling of pressure

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- Central differencing discretisation
- Wide-stencil gradient, divergence & Laplacian



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Equations				

Wide-stencil

Wide & Rhie-Chow

Compact-stencil

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Equations				

Wide-stencil	Wide & Rhie-Chow	Compact-stencil		
$\mathbf{u}_{c}^{p}=R(\mathbf{u}_{c},\mathbf{u}_{s})-G_{c}\widetilde{\mathbf{p}}_{c}^{p}$				

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Equations				

Wide-stencil	Wide & Rhie-Chow	Compact-stencil		
$\mathbf{u}_c^p = R(\mathbf{u}_c,\mathbf{u}_s) - G_c \widetilde{\mathbf{p}}_c^p$				
$L_c  ilde{\mathbf{p}}_c' =$	$M\Gamma_{cs}\mathbf{u}_{c}^{p}$	$L \widetilde{\mathbf{p}}_c' = M \Gamma_{cs} \mathbf{u}_c^p$		

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Equations				

Wide-stencil	Wide & Rhie-Chow	Compact-stencil			
	$\mathbf{u}_c^ ho=R(\mathbf{u}_c,\mathbf{u}_s)-\mathcal{G}_c\widetilde{\mathbf{p}}_c^ ho$				
$L_{c}\tilde{\mathbf{p}}_{c}' = M\Gamma_{cs}\mathbf{u}_{c}^{\rho} \qquad \qquad L\tilde{\mathbf{p}}_{c}' = M\Gamma_{cs}\mathbf{u}_{c}^{\rho}$					
u'	$\mathbf{\tilde{p}}_{c}^{r+1} = \mathbf{u}_{c}^{p} - \mathcal{G}_{c} \mathbf{\tilde{p}}_{c}^{\prime}, \hspace{0.5cm} \mathbf{\tilde{p}}_{c}^{n+1} = \mathbf{\tilde{p}}_{c}^{p} + \mathbf{\tilde{p}}_{c}^{n+1}$	$\tilde{\mathbf{p}}_{c}^{\prime}$			

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Equations				

Wide-stencil	Wide & Rhie-Chow	Compact-stencil			
$\mathbf{u}_c^p = R(\mathbf{u}_c,\mathbf{u}_s) - G_c \widetilde{\mathbf{p}}_c^p$					
$L_c  ilde{\mathbf{p}}_c' =$	$M\Gamma_{cs}\mathbf{u}_{c}^{p}$	$L \widetilde{\mathbf{p}}_c' = M \Gamma_{cs} \mathbf{u}_c^p$			
u <sup>n</sup> a	$\mathbf{\hat{\mu}}^{+1} = \mathbf{u}_c^{p} - \mathit{G}_c \mathbf{ ilde{p}}_c',  \mathbf{ ilde{p}}_c^{n+1} = \mathbf{ ilde{p}}_c^{p} - \mathbf{ ilde{p}}_c'$	$+ \tilde{\mathbf{p}}_{c}'$			
$u^{n+1}_s = \Gamma_{cs} u^{n+1}_c$	$u_s^{n+1} =$	$\Gamma_{cs} \mathbf{u}_{c}^{p} - G \tilde{\mathbf{p}}_{c}^{\prime}$			

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Equations				

Wide-stencil	Wide & Rhie-Chow	Compact-stencil
	$\mathbf{u}_{c}^{p}=R(\mathbf{u}_{c},\mathbf{u}_{s})-G_{c}\mathbf{ ilde{p}}_{c}^{p}$	
$L_c  ilde{\mathbf{p}}_c' =$	$M\Gamma_{cs}\mathbf{u}_{c}^{p}$	$L \widetilde{\mathbf{p}}_c' = M \Gamma_{cs} \mathbf{u}_c^p$
u <sub>c</sub> <sup>n-</sup>	$\mathbf{\mu}^{+1} = \mathbf{\mu}^p_c - G_c \mathbf{\tilde{p}}'_c,  \mathbf{\tilde{p}}^{n+1}_c = \mathbf{\tilde{p}}^p_c + \mathbf{\tilde{p}}^n_c$	$\tilde{\mathbf{P}}_{c}^{\prime}$
$u_s^{n+1} = \Gamma_{cs} u_c^{n+1}$	$u_s^{n+1} = \Gamma_c$	$c_{cs}\mathbf{u}_{c}^{p}-G\widetilde{\mathbf{p}}_{c}^{\prime}$
Checkerboarding	$M {f u}_s^{n+1}  eq {f 0}_c$	$M {f \Gamma}_{cs} {f u}_c^{n+1}  eq {f 0}_c$

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Pressure error				
Pressure error				

- $\bullet\,$  The pressure error is linked to the divergence of u
- For the compact stencil method:  $M\Gamma_{cs}\mathbf{u}_{c}^{n+1}\neq\mathbf{0}_{c}$
- The error arises from the difference in L and  $L_c$

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Pressure error				

#### Pressure error

- $\bullet\,$  The pressure error is linked to the divergence of u
- For the compact stencil method:  $M\Gamma_{cs}\mathbf{u}_{c}^{n+1}\neq\mathbf{0}_{c}$
- The error arises from the difference in L and  $L_c$

$$M_{c}\mathbf{u}_{c}^{n+1} = M\Gamma_{cs}(\mathbf{u}_{c}^{p} - G_{c}\tilde{\mathbf{p}}_{c}')$$

$$M\mathbf{u}_{s}^{n+1} = \mathbf{0}_{c}$$

$$= M(\Gamma_{cs}\mathbf{u}_{c}^{p} - G\tilde{\mathbf{p}}_{c}') + M(G\tilde{\mathbf{p}}_{c}' - \Gamma_{cs}G_{c}\tilde{\mathbf{p}}_{c}')$$

$$= (L - L_{c})\tilde{\mathbf{p}}_{c}'$$

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Objective				

#### Questions

- What are the origins of the oscillations?
- How can we quantify the oscillations?
- Can we design a method that diminishes checkerboarding with less numerical dissipation?

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Mechanism 1: 4	$\Delta t  ightarrow 0^+$			

- Compact-stencil Laplacian method
- No pressure predictor, i.e.  $\tilde{\mathbf{p}}_{c}^{p} = \mathbf{0}_{c}$

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Mechanism 1	: $\Delta t  ightarrow 0^+$			

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- No pressure predictor, i.e.  $\tilde{\mathbf{p}}_{c}^{p} = \mathbf{0}_{c}$

$$\mathbf{u}_{c}^{n+1} = \mathbf{u}_{c}^{p} - G_{c} \tilde{\mathbf{p}}_{c}^{n+1}$$

$$= \mathbf{u}_{c}^{n} - \Delta t [Con + Dif] - G_{c} \tilde{\mathbf{p}}_{c}^{n+1}$$

$$= \mathbf{u}_{c}^{0} - G_{c} \sum_{i=1}^{n+1} \tilde{\mathbf{p}}_{c}^{i}$$

$$= \mathbf{u}_{c}^{0} - G_{c} \mathbb{P}_{c}^{n+1}$$

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Mechanism 1	: $\Delta t  ightarrow 0^+$			

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Just repeatedly pressure correcting!

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Mechanism	1: $\Delta t  ightarrow 0^+$			

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$$= \mathbf{u}_{c}^{0} - G_{c} \sum_{i=1}^{n+1} \tilde{\mathbf{p}}_{c}^{i}$$

$$= \mathbf{u}_{c}^{0} - G_{c} \mathbb{P}_{c}^{n+1}$$

$$\widetilde{\mathbf{p}}_{c}^{n+2} = M_{c}\mathbf{u}_{c}^{0} - L_{c}\mathbb{P}_{c}^{n+1}$$
$$\mathbb{P}_{c}^{n+2} = M_{c}\mathbf{u}_{c}^{0} + (L - L_{c})\mathbb{P}_{c}^{n+1} \downarrow + L\mathbb{P}_{c}^{n+1}$$

Just repeatedly pressure correcting!

Introduction	Origins of checkerboarding	Quantification method	Results	Conclusions
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Mechanism	1: $\Delta t  ightarrow 0^+$			

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$$\mathbf{u}_{c}^{n+1} = \mathbf{u}_{c}^{p} - G_{c} \tilde{\mathbf{p}}_{c}^{n+1}$$

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$$= \mathbf{u}_{c}^{0} - G_{c} \sum_{i=1}^{n+1} \tilde{\mathbf{p}}_{c}^{i}$$

$$= \mathbf{u}_{c}^{0} - G_{c} \mathbb{P}_{c}^{n+1}$$

Just repeatedly pressure correcting!

$$L\tilde{\mathbf{p}}_{c}^{n+2} = M_{c}\mathbf{u}_{c}^{0} - L_{c}\mathbb{P}_{c}^{n+1}$$
$$L\mathbb{P}_{c}^{n+2} = M_{c}\mathbf{u}_{c}^{0} + (L - L_{c})\mathbb{P}_{c}^{n+1} \downarrow + L\mathbb{P}_{c}^{n+1}$$

# Stationary iterative solver

 $L_c \mathbb{P}_c = M_c \mathbf{u}_c^0$  $\rightarrow$  Allows for checkerboarding!

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Me	chanism 2: $\mathbf{p}_{c}^{p} = \mathbf{p}_{c}^{n}$			
Dit	ferent example:			
•	Compact-stencil Laplacian method			
•	$\underline{Pressure predictor:} \; \mathbf{p}_c^p = \mathbf{p}_c^n$			

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Mechanism	2: $\mathbf{p}_{c}^{p} = \mathbf{p}_{c}^{n}$			
Different exa	imple:			

- Compact-stencil Laplacian method
- Pressure predictor:  $\mathbf{p}_c^p = \mathbf{p}_c^n$

$$\mathbf{u}_{c}^{p} = R(\mathbf{u}_{c}, \mathbf{u}_{s}) - G_{c} \tilde{\mathbf{p}}_{c}^{n}$$

$$L \tilde{\mathbf{p}}_{c}' = M_{c} R(\mathbf{u}_{c}, \mathbf{u}_{s}) - L_{c} \tilde{\mathbf{p}}_{c}^{n}$$

$$L_{c} \tilde{\mathbf{p}}_{c}^{n+1} = M_{c} R(\mathbf{u}_{c}, \mathbf{u}_{s}) + (L_{c} - L) \tilde{\mathbf{p}}_{c}'$$

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Mechanism	1 2: $\mathbf{p}_{c}^{p} = \mathbf{p}_{c}^{n}$			
Different ex	ample:			
Compact	-stencil Laplacian method			

• Pressure predictor:  $\mathbf{p}_{c}^{p} = \mathbf{p}_{c}^{n}$ 

$$\mathbf{u}_{c}^{p} = R(\mathbf{u}_{c}, \mathbf{u}_{s}) - G_{c} \tilde{\mathbf{p}}_{c}^{n}$$

$$L \tilde{\mathbf{p}}_{c}' = M_{c} R(\mathbf{u}_{c}, \mathbf{u}_{s}) - L_{c} \tilde{\mathbf{p}}_{c}^{n}$$

$$L_{c} \tilde{\mathbf{p}}_{c}^{n+1} = M_{c} R(\mathbf{u}_{c}, \mathbf{u}_{s}) + (L_{c} - L) \tilde{\mathbf{p}}_{c}' + L_{c} \tilde{\mathbf{p}}_{c}^{n+1} - L \tilde{\mathbf{p}}_{c}'$$

#### Similar problem

- Solving a wide-stencil Laplacian if  $\tilde{\mathbf{p}}_c' \rightarrow \mathbf{0}_c$
- In case of a steady-state solution
- ullet In case  $\Delta t 
  ightarrow 0^+$ , combines well with mechanism 1

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Mechanism 3:	Poisson solver			

• Approximate inverse of L can produce oscillations if  $Im(\tilde{L}^{-1}) \not\perp Ker(L_c)$ 

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Mechanism 3:	Poisson solver			

• Approximate inverse of L can produce oscillations if  $Im(\tilde{L}^{-1}) \not\perp Ker(L_c)$ 

Stationary iterative method as an example:

$$L\tilde{\mathbf{p}}_{c} = (\overline{L} + \hat{L})\tilde{\mathbf{p}}_{c} = M_{c}\mathbf{u}_{c}^{p}$$
  

$$\tilde{\mathbf{p}}_{c}^{k+1} = \overline{L}^{-1}(M_{c}\mathbf{u}_{c}^{p} - \hat{L}\tilde{\mathbf{p}}_{c}^{k})$$
  

$$\tilde{\mathbf{p}}_{c} = \underbrace{\sum_{i=0}^{N_{it}}(I - \overline{L}^{-1}L)^{i}\overline{L}^{-1}}_{\overline{L}^{-1}}M_{c}\mathbf{u}_{c}^{p} - (I - \overline{L}^{-1}L)^{N_{it}}\tilde{\mathbf{p}}_{c}^{0}$$

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Mechanism 3:	Poisson solver			

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# Concluding mechanism

• 
$$\tilde{L}^{-1}$$
, or rather  $\overline{L}^{-1}$  can produce oscillations

•  $\tilde{\mathbf{p}}_c^0$  can preserve them

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Mechanism 3:	Poisson solver			

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$$\tilde{\mathbf{p}}_{c} = \underbrace{\sum_{i=0}^{N_{it}}(I - \overline{L}^{-1}L)^{i}\overline{L}^{-1}}_{\widetilde{L}^{-1}}M_{c}\mathbf{u}_{c}^{p} - (I - \overline{L}^{-1}L)^{N_{it}}\tilde{\mathbf{p}}_{c}^{0}$$

#### Concluding mechanism

- $\tilde{L}^{-1}$ , or rather  $\overline{L}^{-1}$  can produce oscillations
- $\tilde{\mathbf{p}}_c^0$  can preserve them

Similarly, preconditioners can cause oscillations

• 
$$Q_L^{-1}LQ_R^{-1}\tilde{\mathbf{q}}_c^{n+1} = Q_L^{-1}M_c\mathbf{u}_c^p$$

• where 
$$Q_R^{-1} \tilde{\mathbf{q}}_c^{n+1} = \tilde{\mathbf{p}}_c^{n+1}$$

• if  $Im(Q_R^{-1}) \not\perp Ker(L_c)$ 

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Mechanism 4:	Non-symmetries	of operators		

# Inconsistent operators

- Symmetry-preserving:  $M_c = -(\Omega G_c)^T$
- If not,  $L_c = M_c G_c \neq L_c^T$
- And  $Im(L_c) \not\perp Ker(L_c)$

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Mechanism 4: N	lon-symmetries of op	erators		

#### Inconsistent operators

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- If not,  $L_c = M_c G_c \neq L_c^T$
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Oscillations can then enter via the right hand side of the Poisson equation:

$$\mathbf{u}_{c}^{p} = \mathbf{u}_{c}^{n} - \Delta t [Con + Dif] - G_{c} \tilde{\mathbf{p}}_{c}^{p}$$
$$\mathbf{u}_{c}^{p} = \mathbf{u}_{c}^{p,n-1} - G_{c} \tilde{\mathbf{p}}_{c}^{n} - \Delta t [Con + Dif] - G_{c} \tilde{\mathbf{p}}_{c}^{p}$$
$$M_{c} \mathbf{u}_{c}^{p} = M_{c} (\mathbf{u}_{c}^{p,n-1} - \Delta t [Con + Dif]) - L_{c} (\tilde{\mathbf{p}}_{c}^{n} + \tilde{\mathbf{p}}_{c}^{p}) \mathcal{D}_{c} G_{c} = L_{c}$$

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Mechanism 4: I	Non-symmetries of op	perators		

#### Inconsistent operators

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$$M_{c} \mathbf{u}_{c}^{p} = M_{c} (\mathbf{u}_{c}^{p,n-1} - \Delta t [Con + Dif]) - L_{c} (\tilde{\mathbf{p}}_{c}^{n} + \tilde{\mathbf{p}}_{c}^{p}) \downarrow M_{c} G_{c} = L_{c}$$

This also means SP-method automatically filters these type of oscillations!

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Mechanisms	of interest			

# Focus on mechanism 1 & 2

 $\checkmark$  1.  $\Delta t \rightarrow 0^+$ 

$$\checkmark 2. ~ \tilde{\mathbf{p}}_c^p = \theta_p \tilde{\mathbf{p}}_c^n, \quad \theta_p \in [0, 1]$$

 $\times$  3. Poisson solver

limited oscillations observed

 $\times$  4. Non-symmetries of operators f

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Strict definition				ľ

Oscillations are *invisible* to  $G_c$ Related to  $Ker(L_c)$ However, definitions from  $Ker(L_c)$  are inadequate:

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Strict definit	tion			
Oscillations are	<i>invisible</i> to $G_c$			

Related to  $Ker(L_c)$ However, definitions from  $Ker(L_c)$  are inadequate:

# $Ker(L_c)$ is inadequate when:

• Complex mesh

$$ightarrow$$
 Ker(L<sub>c</sub>)vanishes

- Certain boundary conditions
- Oscillations occur locally  $\rightarrow$  (nearly/fully) orthogonal to  $Ker(L_c)$

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Strict defini	tion			
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• Complex mesh

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Broader definition	on			

 $-\mathbf{u}_{c}^{T}\Omega G_{c}\mathbf{p}_{c}$ 

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Broader definition	on			

$$-\mathbf{u}_{c}^{T}\Omega G_{c}\mathbf{p}_{c}=\mathbf{p}_{c}^{T}M_{c}\mathbf{u}_{c}$$

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Broader definition	on			

$$-\mathbf{u}_{c}^{T}\Omega G_{c}\mathbf{p}_{c}=\mathbf{p}_{c}^{T}M_{c}\mathbf{u}_{c}=\Delta t\mathbf{p}_{c}^{T}(L-L_{c})$$

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Broader definition	on			

$$-\mathbf{u}_{c}^{T}\Omega G_{c}\mathbf{p}_{c}=\mathbf{p}_{c}^{T}M_{c}\mathbf{u}_{c}=\Delta t\mathbf{p}_{c}^{T}(L-L_{c})\mathbf{p}_{c}\in[\Delta t\mathbf{p}_{c}^{T}L\mathbf{p}_{c},0]$$

Which is strictly dissipative.

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Broader definition	on			

$$-\mathbf{u}_{c}^{\mathsf{T}}\Omega G_{c}\mathbf{p}_{c}=\mathbf{p}_{c}^{\mathsf{T}}M_{c}\mathbf{u}_{c}=\Delta t\mathbf{p}_{c}^{\mathsf{T}}(L-L_{c})\mathbf{p}_{c}\in[\Delta t\mathbf{p}_{c}^{\mathsf{T}}L\mathbf{p}_{c},0]$$

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$$-\mathbf{u}_{c}^{\mathsf{T}}\Omega G_{c}\mathbf{p}_{c}=\mathbf{p}_{c}^{\mathsf{T}}M_{c}\mathbf{u}_{c}=\Delta t\mathbf{p}_{c}^{\mathsf{T}}(L-L_{c})\mathbf{p}_{c}\in[\Delta t\mathbf{p}_{c}^{\mathsf{T}}L\mathbf{p}_{c},0]$$

$$C_{cb} = 1 - rac{\mathbf{p}_c^T L_c \mathbf{p}_c}{\mathbf{p}_c^T L \mathbf{p}_c}$$

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$$-\mathbf{u}_{c}^{\mathsf{T}}\Omega G_{c}\mathbf{p}_{c}=\mathbf{p}_{c}^{\mathsf{T}}M_{c}\mathbf{u}_{c}=\Delta t\mathbf{p}_{c}^{\mathsf{T}}(L-L_{c})\mathbf{p}_{c}\in[\Delta t\mathbf{p}_{c}^{\mathsf{T}}L\mathbf{p}_{c},0]$$

$$C_{cb} = 1 - \frac{\mathbf{p}_c^T L_c \mathbf{p}_c}{\mathbf{p}_c^T L \mathbf{p}_c} = 1 - \frac{\mathbf{p}_c^T G_c^T \Omega G_c \mathbf{p}_c}{\mathbf{p}_c^T G^T \Omega_s G \mathbf{p}_c}$$

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Broader definition	on			

$$-\mathbf{u}_{c}^{\mathsf{T}}\Omega G_{c}\mathbf{p}_{c}=\mathbf{p}_{c}^{\mathsf{T}}M_{c}\mathbf{u}_{c}=\Delta t\mathbf{p}_{c}^{\mathsf{T}}(L-L_{c})\mathbf{p}_{c}\in[\Delta t\mathbf{p}_{c}^{\mathsf{T}}L\mathbf{p}_{c},0]$$

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Broader definition	on			

$$-\mathbf{u}_{c}^{\mathsf{T}}\Omega G_{c}\mathbf{p}_{c}=\mathbf{p}_{c}^{\mathsf{T}}M_{c}\mathbf{u}_{c}=\Delta t\mathbf{p}_{c}^{\mathsf{T}}(L-L_{c})\mathbf{p}_{c}\in[\Delta t\mathbf{p}_{c}^{\mathsf{T}}L\mathbf{p}_{c},0]$$

$$C_{cb} = 1 - \frac{\mathbf{p}_c^T L_c \mathbf{p}_c}{\mathbf{p}_c^T L \mathbf{p}_c} = 1 - \frac{\mathbf{p}_c^T G_c^T \Omega G_c \mathbf{p}_c}{\mathbf{p}_c^T G^T \Omega_s G \mathbf{p}_c} = 1 - \frac{||G_c \mathbf{p}_c||}{||G \mathbf{p}_c||} \in [0, 1]$$

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Broader definition	on			

$$-\mathbf{u}_{c}^{\mathsf{T}}\Omega G_{c}\mathbf{p}_{c}=\mathbf{p}_{c}^{\mathsf{T}}M_{c}\mathbf{u}_{c}=\Delta t\mathbf{p}_{c}^{\mathsf{T}}(L-L_{c})\mathbf{p}_{c}\in[\Delta t\mathbf{p}_{c}^{\mathsf{T}}L\mathbf{p}_{c},0]$$

$$C_{cb} = 1 - \frac{\mathbf{p}_c^T \mathcal{L}_c \mathbf{p}_c}{\mathbf{p}_c^T \mathcal{L} \mathbf{p}_c} = 1 - \frac{\mathbf{p}_c^T G_c^T \Omega G_c \mathbf{p}_c}{\mathbf{p}_c^T G^T \Omega_s G \mathbf{p}_c} = 1 - \frac{||G_c \mathbf{p}_c||}{||G \mathbf{p}_c||} \in [0, 1] \begin{cases} 0, & \text{smooth} \\ 1, & \text{fully in } Ker(\mathcal{L}_c) \end{cases}$$

Introduction	Origins of checkerboarding	Quantification method	Results	Conclusions
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Broader definiti	on			

$$-\mathbf{u}_{c}^{\mathsf{T}}\Omega G_{c}\mathbf{p}_{c}=\mathbf{p}_{c}^{\mathsf{T}}M_{c}\mathbf{u}_{c}=\Delta t\mathbf{p}_{c}^{\mathsf{T}}(L-L_{c})\mathbf{p}_{c}\in[\Delta t\mathbf{p}_{c}^{\mathsf{T}}L\mathbf{p}_{c},0]$$

Which is strictly dissipative. Dividing out  $\Delta t \mathbf{p}_c^T L \mathbf{p}_c$ :

$$C_{cb} = 1 - \frac{\mathbf{p}_c^T \mathcal{L}_c \mathbf{p}_c}{\mathbf{p}_c^T \mathcal{L} \mathbf{p}_c} = 1 - \frac{\mathbf{p}_c^T G_c^T \Omega G_c \mathbf{p}_c}{\mathbf{p}_c^T G^T \Omega_s G \mathbf{p}_c} = 1 - \frac{||G_c \mathbf{p}_c||}{||G \mathbf{p}_c||} \in [0, 1] \begin{cases} 0, & \text{smooth} \\ 1, & \text{fully in } Ker(\mathcal{L}_c) \end{cases}$$

# Checkerboard coefficient $C_{cb}$

- Global, non-dimensional, normalised, time-step independent
- Able to detect local oscillations

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$\theta_{\textit{cb}}$ -solver				

We set  $\theta_p$  in the momentum predictor:

$$\mathbf{u}_c^p = R(\mathbf{u}_c^n, \mathbf{u}_s^n) - G_c \tilde{\mathbf{p}}_c^p = R(\mathbf{u}_c^n, \mathbf{u}_s^n) - G_c \frac{\theta_p}{\rho} \tilde{\mathbf{p}}_c^n$$

Which is also non-dimensional and  $\in [0, 1]$ . A new solver can be derived by setting  $\theta_p$  dynamically as  $\theta_p = 1 - C_{cb}$ .

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$\theta_{\textit{cb}}\text{-solver}$				

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# $\theta_{cb}$ -solver

- Higher  $\theta_p$  is a known cause of checkerboarding
- Negative feedback through  $C_{cb}$  can auto-regulate the problem

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$\theta_{\textit{cb}}\text{-solver}$				

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# $\theta_{cb}$ -solver

- Higher  $\theta_p$  is a known cause of checkerboarding
- Negative feedback through  $C_{cb}$  can auto-regulate the problem

Overview of tested solvers: 
$$\begin{array}{c|c} Solver & \theta_0 & \theta_1 & \theta_{cb} \\ \hline \theta_p & 0 & 1 & 1 - C_{cb} \end{array}$$

Introduction 0000 Origins of checkerboarding

Quantification metho

Results ●000 Conclusions 00

# 2D Taylor-Green vortex



![](_page_48_Picture_1.jpeg)

![](_page_48_Figure_2.jpeg)

![](_page_49_Figure_0.jpeg)

Time

troduction 000	Origins of checkerboarding	Quantification method	Results 0●00	Conclusion: OO
id-driven c	avitv			

![](_page_50_Figure_1.jpeg)

![](_page_51_Figure_1.jpeg)

![](_page_51_Figure_2.jpeg)

Introduction 0000	Origins of checkerboarding 00000	Quantification method	Results 00●0	Conclusions OO
_id-driv	ven cavity			
	$\theta_0$			
	$\theta_1$	- 1.4e+00 - 1 - 0.5		
e		0.5 8.1e-01		

![](_page_53_Figure_0.jpeg)

1.0 17 / 20

 $\theta_{cb}$ 

-0.075

-0.100

0.2 0.4 0.6 0.8

х

![](_page_54_Figure_0.jpeg)

17 / 20

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Channel flow at	$\mathit{Re}_{ au} = 180$			

![](_page_55_Figure_1.jpeg)

Introduction	Origins of checkerboarding	Quantification method	Results	Conclusions
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Channel flow at	$Re_{ au}=180$			

![](_page_56_Figure_1.jpeg)

![](_page_56_Figure_2.jpeg)

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# Channel flow at $Re_{ au} = 180$

![](_page_57_Figure_2.jpeg)

![](_page_57_Figure_3.jpeg)

![](_page_57_Figure_4.jpeg)

troduction Origins of checkerboarding Quantification method Results Conclusions 000 000 000 000 000 000 000 000 000

# Channel flow at $Re_{ au} = 180$

![](_page_58_Figure_2.jpeg)

![](_page_58_Figure_3.jpeg)

![](_page_58_Figure_4.jpeg)

# Conclusions

- More oscillations in general, most for  $\theta_1$
- $\theta_{cb}$  settles closer to  $\theta_0$

Introduction	Origins of checkerboarding	Quantification method	Results	Conclusions
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Conclusions				

- $\Delta t 
  ightarrow 0^+$
- $\tilde{\mathbf{p}}_{c}^{p} = \theta_{p} \tilde{\mathbf{p}}_{c}^{n}, \quad \theta_{p} \in [0, 1]$
- Poisson solver
- Non-symmetries of operators

Introduction	Origins of checkerboarding	Quantification method	Results	Conclusions
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Conclusions				

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# Quantification method

- *Ker*(*L<sub>c</sub>*) is inadequate for quantifying and filtering
- C<sub>cb</sub> offers a global non-dimensional normalised coefficient, independent of time-step

Introduction	Origins of checkerboarding	Quantification method	Results	Conclusions
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Conclusions				

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#### $\theta_{cb}$ -solver

- C<sub>cb</sub> offers a negative feedback on  $\tilde{\mathbf{p}}_c^p$  and auto-regulates oscillations
- Almost no numerical dissipation in absence of oscillations
- $\bullet$  Diminishes oscillations where  $\theta_{p}=1$  suffers

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Conclusions				

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# Outlook

- Can we use a local *C<sub>cb</sub>* to diminish oscillations locally?
- How does it compare to other, generalised Rhie-Chow interpolation methods?
- What if the origin is different form  $\tilde{\mathbf{p}}_c^p$ ?

Introduction 0000

Questions?

Origins of checkerboarding

Quantification meth

Results 0000 Conclusions 00

Thank you for attending! Any questions?

![](_page_63_Figure_6.jpeg)