

On self-adaptive Runge-Kutta Schemes with Improved Energy-Conservation Properties

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Introduction

CFL¹

First used method to ensure the stability of an explicit integration

$$\frac{du}{dt} + u \frac{du}{dx} = 0$$



$$\left(\frac{u\Delta t}{\Delta x}\right)_{max} \leq 1$$

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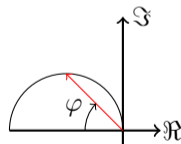
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SAT²

Computation of the eigenbounds in the predictor velocity step to set the maximum stable Δt



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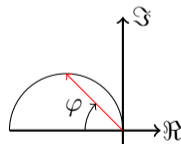
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Introduction

Energy-preserving simulations

- Conservation in space has been widely studied, by Verstappen and Veldman³ and Trias et al.⁴.
 - Sets how operators have to be constructed.
- But... conservation in time?
 - Sande⁵ applied symplectic Runge-Kutta schemes → implicit integrators
 - Capuano et al.⁶ used pseudo-symplectic schemes: explicit, conservation of energy up until a certain order q

³Verstappen, R.W.C.P, Veldman, A.E.P. (2003), "Symmetry-preserving discretization of turbulent flow". Journal of Computational Physics 187 (1), pp. 343-368

⁴Trias, F.X. et al. (2014), "Symmetry-preserving discretization of Navier-Stokes equations on collocated unstructured grids". Journal of Computational Physics 258, pp. 24-267

⁵Sande, B. (2013), "Energy-conserving Runge-Kutta methods for the incompressible Navier-Stokes equations". Journal of Computational Physics 233 (1), pp. 100-131

⁶Capuano, F. et al. (2016), "Explicit Runge-Kutta schemes for incompressible flow with improved energy-conservation properties". Journal of Computational Physics 328, pp. 86-94

Runge-Kutta applied to Navier-Stokes

Starting point...

$$Mu_s = 0_c$$

$$\Omega \frac{du_c}{dt} + C(u_s)u_c - Du_c + \Omega G_c p_c = 0_c$$

- Putting together both expressions...

$$\frac{du_c}{dt} = \underbrace{(I_n - GL^{-1}M)}_{\text{Projection operator, } P} F(u_s)u_c$$

- Hard to compute $PF(u_s)$, thus projection method is used.

According to Sanderse and Koren ⁵,

$$u_i^* = u_n + \Delta t \sum_{j=1}^{i-1} a_{ij} F_j \quad u_{n+1}^* = u_n + \Delta t \sum_{i=1}^s b_i F_i$$

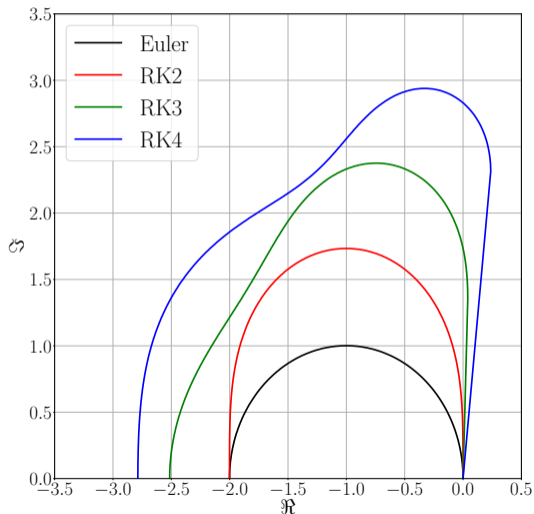
$$L\Psi_i = \frac{1}{\Delta t} Du_i^* \quad L\Psi_{n+1} = \frac{1}{\Delta t} Du_{n+1}^*$$

$$u_i = u_i^* - \Delta t G\Psi_i \quad u_{n+1} = u_{n+1}^* - \Delta t G\Psi_{n+1}$$

⁵Sanderse, B., Koren, B. (2012), "Accuracy analysis of explicit Runge-Kutta methods applied to the incompressible Navier-Stokes equations", Journal of Computational Physics 231 (8), pp. 3041-3063

Stability region of Runge-Kutta

- Coefficients a_{ij}, b_i from the method:
Butcher tableau, $A = [a_{ij}]_{i=1, \dots, s; j=1, \dots, s}$,
 $b = (b_1 \ b_2 \ \dots \ b_s)$
- In general, $R(z) = 1 + zb^T(I_s - zA)^{-1}\mathbf{1}_s$,
yet for $p = s$, $R(z) = 1 + \sum_{p=1}^s \frac{1}{p!} z^p$



Computation of eigenbounds

- Need to compute the eigenbounds of $F(u_s) = D - C(u_s)$
- If D and $C(u_s)$ are discretized with a symmetry-preserving scheme²,

$$\lambda_F \leq -|\rho(D)| + i\rho(C)$$

- $\rho(D)$ and $\rho(C)$ can be computed independently with Gershgorin circle theorem

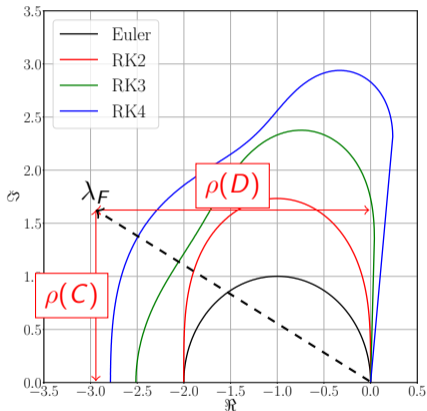
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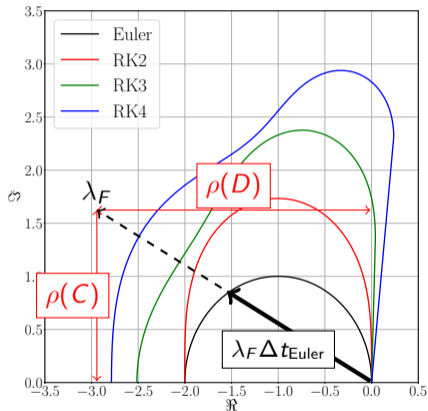
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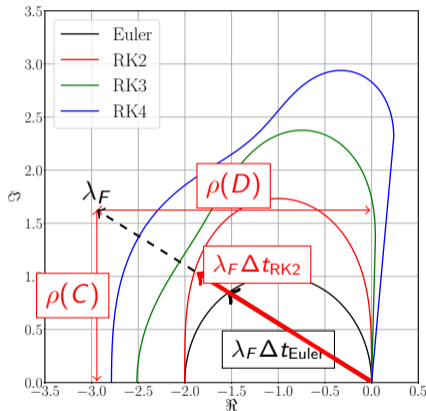
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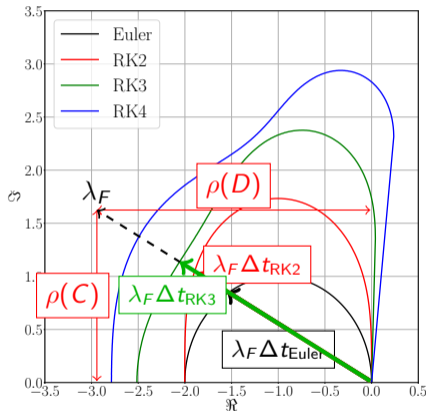
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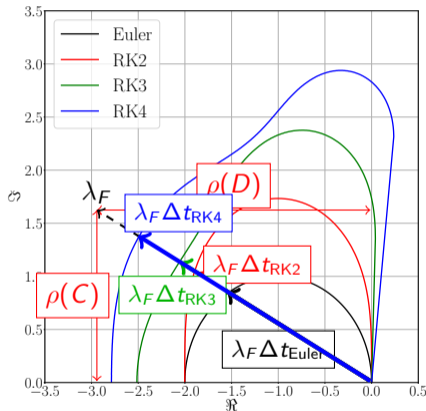
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Computation of eigenbounds

Construction of operators

$$D_c(\alpha_s) = -T_{sc} A_s \Lambda_s \Delta_s^{-1} T_{cs} = -T_{sc} \tilde{\Lambda}_s T_{cs}$$

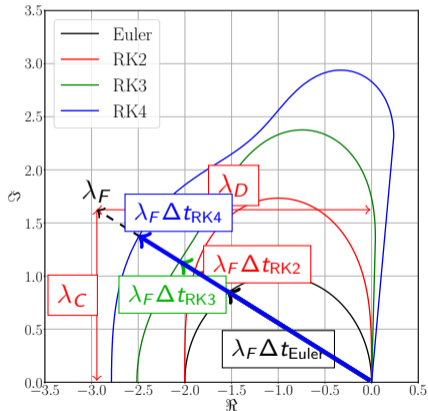
$$C_c(u_s) = T_{sc} A_s U_s \Pi_{c \rightarrow s} \underbrace{=}_{SP} \frac{1}{2} A_s U_s |T_{cs}|$$

By knowing $\rho(AB) = \rho(A^T B^T)$

$$\rho(D_c) = \rho(-\tilde{\Lambda}^\alpha T_{cs} T_{cs}^T \tilde{\Lambda}^{1-\alpha})$$

$$4\rho(C_c(u_s)) \leq \rho(|F_s|^\alpha |T_{cs} T_{cs}^T| |F_s|^{1-\alpha})$$

- Allows recomputing the eigenbounds without the reconstruction of D_c , C_c



Kinetic energy budget for the Navier-Stokes equations

- Conservation of energy is a **requirement** for a physics-compatible solver

Semi-discrete Kinetic energy equation

$$u_c^T \Omega \frac{du_c}{dt} = -u_c^T C(u_s) u_c - u_c^T G_c p_c + u_c^T D u_c$$

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So... integrated in time with Runge-Kutta...

$$\frac{\Delta E}{\Delta t} = - \sum_{i=1}^s b_i u_i^T C_i u_i - \sum_{i=1}^s b_i u_i^T G_c p_i + \sum_{i=1}^s b_i u_i^T D u_i + \varepsilon_{RK}$$

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- $\sum_{i=1}^s b_i u_i^T G_c p_i = 0$ if $M u_i = 0$ and mesh is staggered

Effective Reynolds number

Definition

First introduced by Capuano et al.⁶,

$$\text{Re}_{\text{eff}} = \frac{\sum_{i=1}^s b_i u_i^T L u_i}{\Delta E / \Delta t}$$

- $D = \frac{1}{\text{Re}} L$

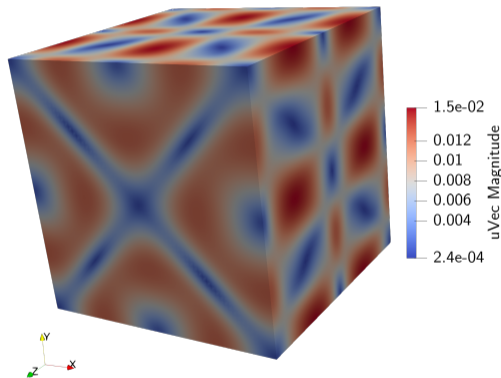
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Numerical experiments

Three-dimensional Taylor-Green vortex

- $2\pi \times 2\pi \times 2\pi$ domain, 32^3 grid
- $f_{\Delta t} = [0.15, 0.25, 0.35, 0.45, 0.5]$
- $Re=1500$
- TermoFluids Algebraic

Scheme	p	q	s
Euler		1	
Heun RK2		2	
Heun RK3		3	
Standard RK4		4	
$4p7q(6)^6$	4	7	6

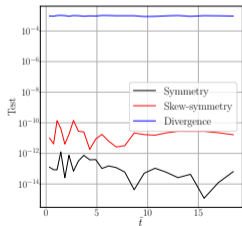
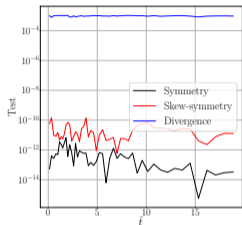


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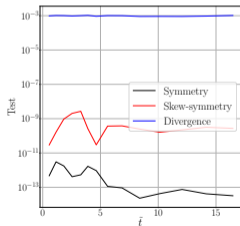
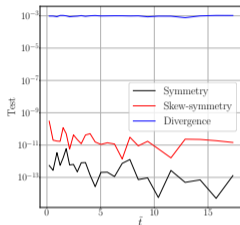
Numerical experiments

Symmetry-preserving discretization

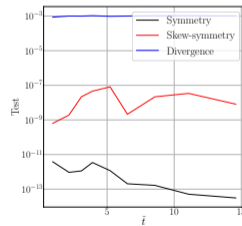
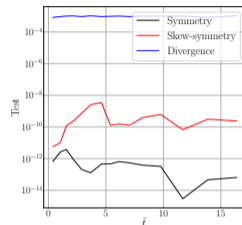
Heun RK2



(a) $f_{\Delta t} = 0.15$



(b) $f_{\Delta t} = 0.25$



(c) $f_{\Delta t} = 0.45$

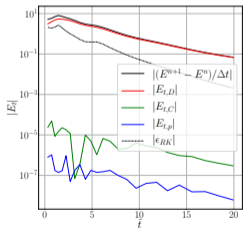
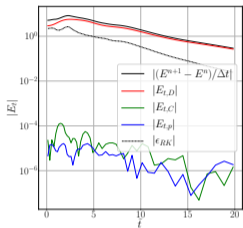
Standard RK4

Numerical experiments

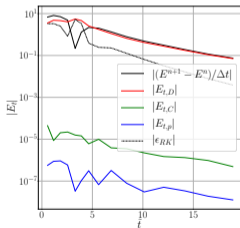
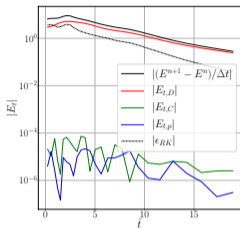
Energy budgets

Heun RK2

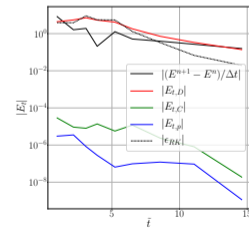
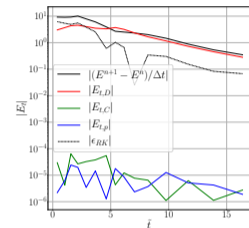
Standard RK4



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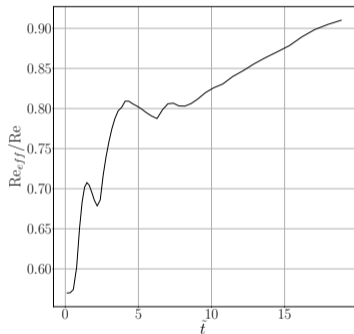
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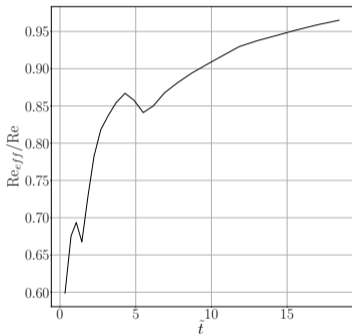
(c) $f_{\Delta t} = 0.45$

Numerical experiments

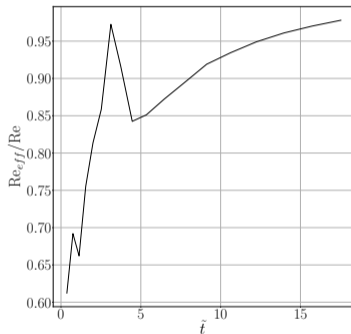
Effective Reynolds number



(a) Heun RK2



(b) Standard RK4



(c) 4p7q(6)

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 - Which is the weight of the RK scheme?
 - For $Re=1500$, variation of $\approx 8\%$ between RK2 and pseudo-symplectic (4p7q(6)), and $\approx 3\%$ between RK4 and 4p7q(6)
 - Implementation shows negligible contributions of both pressure and convective terms
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 - Extra computational cost due to added stages in integration.