

High-order symmetry-preserving discretizations: application to repeated matrix-block structures

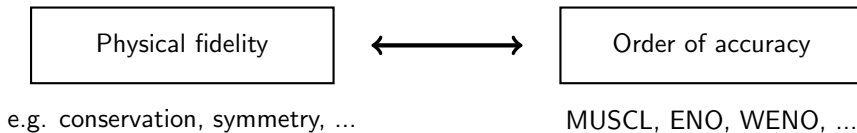
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Heat and Mass Transfer Technological Centre
Technical University of Catalonia

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Introduction



Introduction

High-order symmetry-preserving discretizations

Physical fidelity

e.g. conservation, symmetry, ...



Order of accuracy

MUSCL, ENO, WENO, ...

Introduction

- Given a 1D domain discretized with N cells, a second-order FV discretization leads to...

High-order symmetry-preserving

Fidelity



Accuracy

$$\begin{pmatrix} D_{11} & D_{12} & 0 & \cdots & \cdots & 0 & D_{1N} \\ D_{21} & D_{22} & D_{23} & \cdots & \cdots & 0 & 0 \\ 0 & D_{32} & D_{33} & D_{34} & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ D_{N1} & 0 & \cdots & \cdots & 0 & D_{N,N-1} & D_{N,N} \end{pmatrix}$$

Introduction

- Given a 1D domain discretized with N cells, a fourth-order FV discretization leads to...

High-order symmetry-preserving

Fidelity

↔

Accuracy

$\left(\begin{array}{ccccccc} D_{11} & D_{12} & D_{13} & \cdots & \cdots & D_{1,N-1} & D_{1N} \\ D_{21} & D_{22} & D_{23} & D_{24} & \cdots & \cdots & D_{2N} \\ D_{31} & D_{32} & D_{33} & D_{34} & D_{35} & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ D_{N1} & D_{N2} & \cdots & \cdots & D_{N,N-2} & D_{N,N-1} & D_{N,N} \end{array} \right)$

High-order discretizations lead to **denser** matrices

- For a given mesh, more expensive linear algebra operations.
- Is there any way to exploit this?

Towards high-order symmetry-preserving discretizations

Second-order symmetry-preserving discretizations

The second-order symmetry-preserving discretization of the 1D diffusion operator is constructed as:

$$\left. \frac{\partial^2 \phi}{\partial x^2} \right|_{x_i} = \frac{1}{h} \left(\left. \frac{\partial \phi}{\partial x} \right|_{x_{i+1/2}} - \left. \frac{\partial \phi}{\partial x} \right|_{x_{i-1/2}} \right) + \mathcal{O}(h^2) = \overline{\left. \frac{\partial^2 \phi}{\partial x^2} \right|_{x_i}} + \mathcal{O}(h^2)$$

Interpretation

The second-order approximation of the second derivative can be interpreted as applying a box filter to the second derivative.

Towards high-order symmetry-preserving discretizations

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Interpretation

The second-order approximation of the second derivative can be interpreted as applying a box filter to the second derivative.

Box filter with length h

$$\bar{\phi} = \frac{1}{h} \int_{x-h/2}^{x+h/2} \phi \, dx$$

$$\phi = \bar{\phi} + \frac{h^2}{24} \frac{\partial^2 \phi}{\partial x^2} + \mathcal{O}(h^4)$$

Towards high-order symmetry-preserving discretizations

Fourth-order symmetry-preserving discretizations

According to Trias et al. ¹, this box filter can be applied in such a way that

$$\frac{\partial^2 \phi}{\partial x^2} \approx \overline{\frac{\partial^2 \bar{\phi}}{\partial x^2}} + \overline{\frac{\partial^2 \phi'}{\partial x^2}} + \left(\frac{\partial^2 \bar{\phi}}{\partial x^2} \right)' + \left(\frac{\partial^2 \phi'}{\partial x^2} \right)' + \mathcal{O}(h^4)$$

Extension to multiple dimensions

$$\nabla^2 \phi \approx \overline{\nabla^2 \bar{\phi}} + \overline{\nabla^2 \phi'} + (\nabla^2 \bar{\phi})' + (\nabla^2 \phi')' + \mathcal{O}(h^4)$$

Extension to discrete formulation

$$\tilde{L} = L + LR + RL + RLR = (I + R)L(I + R)$$

¹Trias et al., 2024, Symmetry-preserving approximate deconvolutions. On: 9th European Congress on Computational Methods in Applied Sciences and Engineering (ECCOMAS 2024), Lisbon, Portugal, 3-7 June 2024.

Higher-order symmetry-preserving discretizations

Obtention of M , G , Π , C

Second-order diffusive operator

$$L = MG$$

With this definition, $\tilde{M}$ and $\tilde{G}$ can be obtained from $\tilde{L}$ as:

Fourth-order diffusive operator

$$\tilde{L} = \tilde{M}\tilde{G}$$

- $\tilde{M} = (I + R)M$
- $\tilde{G} = G(I + R)$

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Second-order convective operator

$$C = MU_s\Pi$$

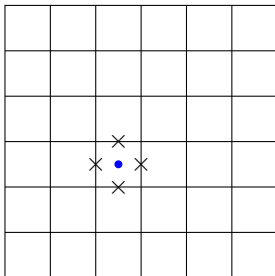
Similarly, $\tilde{C} = (I + R)C(I + R)$. With this definition, $\tilde{M}$, $\tilde{\Pi}$ can be obtained from $\tilde{C}$ as:

Fourth-order convective operator

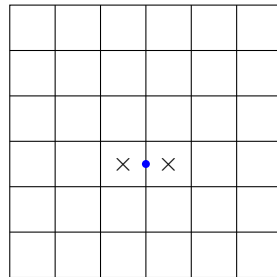
$$\tilde{C} = \tilde{M}U_s\tilde{\Pi}$$

- $\tilde{M} = (I + R)M$
- $\tilde{\Pi} = \Pi(I + R)$

Higher-order symmetry-preserving discretizations

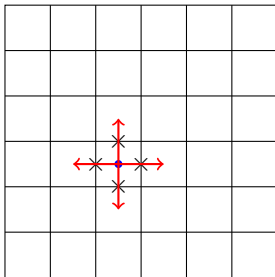


M : 6 entries

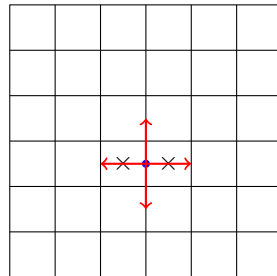


G, Π : 2 entries

Higher-order symmetry-preserving discretizations

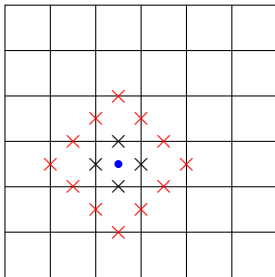


$\tilde{M}$: ? entries

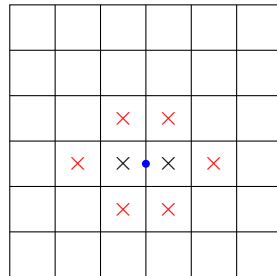


$\tilde{G}, \tilde{\Pi}$: ? entries

Higher-order symmetry-preserving discretizations



$\tilde{M}$: 16 entries



$\tilde{G}, \tilde{N}$: 8 entries

Higher-order symmetry-preserving discretizations

	M	$\tilde{M}$	G, Π	$\tilde{G}, \tilde{\Pi}$	L	$\tilde{L}$	C	$\tilde{C}$
$1D$	2	4	2	4	3	5	2	4
$2D^{tri}$	3	9	2	6	4	19	3	18
$2D^{quad}$	4	16	2	8	5	25	4	24
$3D^{hex}$	6	36	2	12	7	63	6	62

Application to a projection method

Incompressibility constraint in projection methods

$$L\mathbf{p}_c = M\mathbf{u}_c^p$$

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Extending to fourth-order symmetry-preserving discretizations

$$\tilde{L}\tilde{\mathbf{p}}_c = \tilde{M}\tilde{\mathbf{u}}_c^p$$

where $\tilde{\mathbf{x}}$ approximates $\mathbf{x}$ with fourth-order accuracy: $\mathbf{x} = (I + R)\tilde{\mathbf{x}}$.

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$$(I + R)L(I + R)\tilde{\mathbf{p}}_c = (I + R)\tilde{M}\tilde{\mathbf{u}}_c^p$$

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Outcome:

The Poisson equation does not change when using fourth-order symmetry-preserving discretizations.

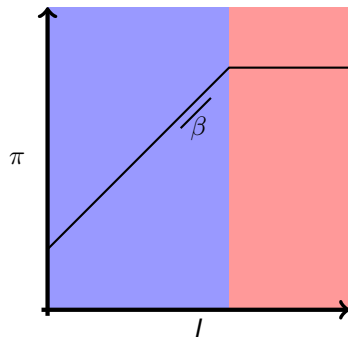
Exploiting repeated matrix-block structures

Roofline model²

$$\pi = \beta l$$

- π : performance
- β : memory bandwidth
- l : arithmetic intensity, flops per byte

$$\underbrace{Ax}_{A=l_2 \otimes \tilde{A}} \underset{\text{SpMV}}{=} \begin{pmatrix} \tilde{A} & 0 \\ 0 & \tilde{A} \end{pmatrix} \begin{pmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \end{pmatrix}$$



²Williams et al., 2009, Roofline: an insightful visual performance model for multicore architectures, Communications of the ACM 52

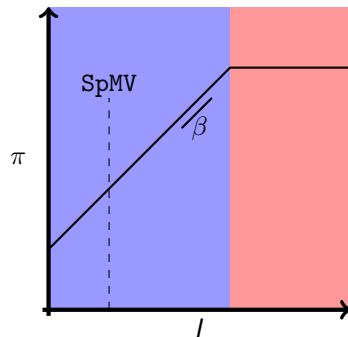
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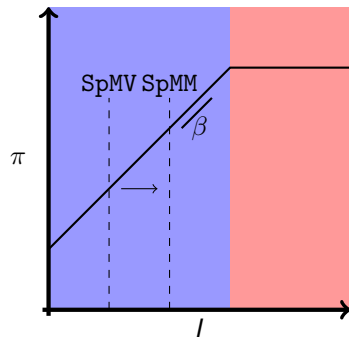
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$$\underbrace{A \mathbf{x} \equiv \underbrace{\begin{pmatrix} \tilde{A} & 0 \\ 0 & \tilde{A} \end{pmatrix} \begin{pmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \end{pmatrix}}_{A = I_2 \otimes \tilde{A}}}_{\text{SpMV}} \equiv \underbrace{\tilde{A} \begin{pmatrix} \mathbf{x}_1 & \mathbf{x}_2 \end{pmatrix}}_{\text{SpMM}}$$



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Exploiting repeated matrix-block structures

Defining the optimal (upper-bound) speed-up as:

$$P_m = \frac{\pi_m}{\pi_1} = \frac{l_{\text{SpMM}}(m)}{l_{\text{SpMV}}}$$

By definition,

$$l_{\text{SpMM}}(m) = \frac{(2\text{nnz}(A) + 1)m}{12\text{nnz}(A) + 4(n_r/m + 1) + 8(n_r + n_c + m)},$$

Then,

$$P_m = \frac{m[3(\text{nnz}(A) + n_r + 1) + 2n_c]}{3\text{nnz}(A) + (1 + 2m)(n_r + 1) + 2mn_c}.$$

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What happens when $m \rightarrow \infty$?

Assuming $n_r \gg 1$ and $n_c = n_r$,

$$\lim_{m \rightarrow \infty} P_m \approx \frac{12\text{nnz}(A)/n_r + 20}{16}$$

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- Upper-bound speed-up depends on density of the matrix.

	M	$\tilde{M}$	G, Π	$\tilde{G}, \tilde{\Pi}$
$2D^{\text{quad}}$	4	16	2	8
$3D^{\text{hex}}$	6	36	2	12

Exploiting repeated matrix-block structures

Reformulating the Navier-Stokes equations

Semi-discrete incompressible Navier-Stokes equations

$$M\mathbf{u}_s = \mathbf{0}_s,$$

$$\Omega \frac{d\mathbf{u}_c}{dt} + MU_s \Pi \mathbf{u}_c = D\mathbf{u}_c - \Omega G_c \mathbf{p}_c$$

³Alsalti-Baldellou et al., 2024, A multigrid reduction framework for domains with symmetries, SIAM Journal on Scientific Computing 46

⁴Plana-Riu et al., 2025, Exploiting repeated matrix-block structures for more efficient CFD on modern supercomputers, arXiv:2508.06710 [preprint]

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Let $\mathbf{U}_c = [\mathbf{u}_{c,1}, \mathbf{u}_{c,2}, \dots, \mathbf{u}_{c,m}]$ and $\mathbf{P}_c = [\mathbf{p}_{c,1}, \mathbf{p}_{c,2}, \dots, \mathbf{p}_{c,m}]$

(Block-structure) semi-discrete incompressible Navier-Stokes equations

$$M\mathbf{U}_s = \mathbf{0}_s,$$

$$\Omega \frac{d\mathbf{U}_c}{dt} + MU_s \Pi \mathbf{U}_c = D\mathbf{U}_c - \Omega G_c \mathbf{P}_c$$

e.g. domains with symmetries or repeated geometries³, parallel-in-time⁴ simulations, etc.

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Exploiting repeated matrix-block structures

Ensemble averaging of multiple flow states

Required condition⁵

Ergodicity: time average = Ensemble average

⁵Tosi et al., 2022, On the use of ensemble averaging techniques to accelerate the Uncertainty Quantification of CFD predictions in wind engineering, Journal of Wind Engineering and Industrial Aerodynamics 228

Exploiting repeated matrix-block structures

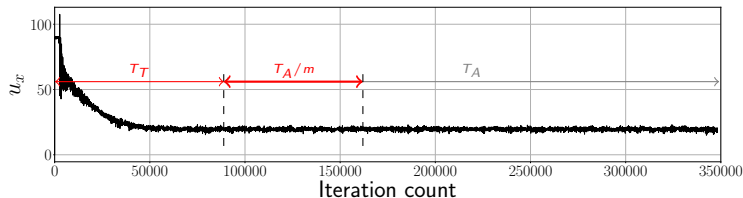
Ensemble averaging of multiple flow states

Required condition⁵

Ergodicity: time average = Ensemble average

Let ϕ be the variable of interest, then:

$$\langle \phi \rangle = \frac{1}{T_A} \int_{T_T}^{T_T+T_A} \phi \, dt \equiv \frac{1}{m} \sum_{i=1}^m \frac{1}{T_A/m} \int_{T_T}^{T_T+T_A/m} \phi_i \, dt$$



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Numerical experiments

Turbulent planar channel flow: numerical setup

- Domain: $L_x \times L_y \times L_z = 4\pi\delta \times 2\delta \times 4\pi\delta/3$
- Grid: $N_x \times N_y \times N_z = 128 \times 128 \times 128$ (2.1 million nodes)
- $Re_\tau = u_\tau\delta/\nu = 180$
- Time integration: RK3 + AlgEigCD
- Initial condition: parabolic profile + random perturbation
- Boundary conditions: periodic in x and z , no-slip in y
- Code: `tfa+hpc2`
- Discretization strategies:
 - Second-order symmetry-preserving (SP2)
 - Fourth-order symmetry-preserving (SP4)

Numerical experiments

Turbulent planar channel flow: numerical setup

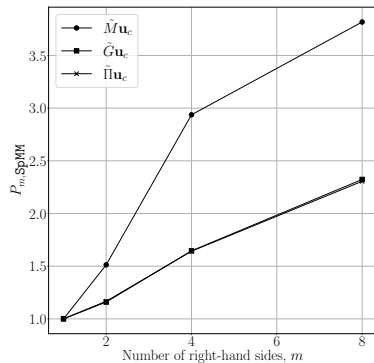
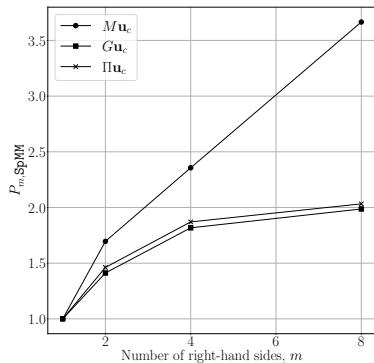
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Objective of the test

Assess the speed-up improvements for the SP4 discretization compared to SP2 when exploiting repeated matrix-block structures.

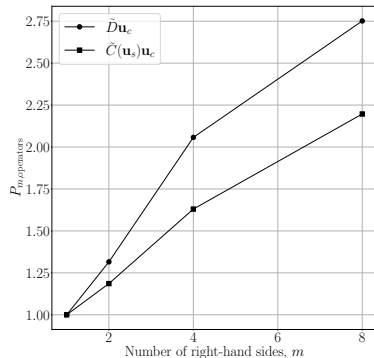
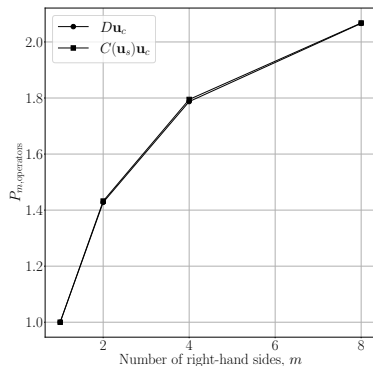
Numerical experiments

Turbulent planar channel flow: M , G , Π results



Numerical experiments

Turbulent planar channel flow: C , D results

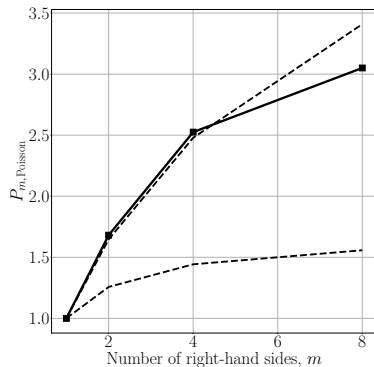
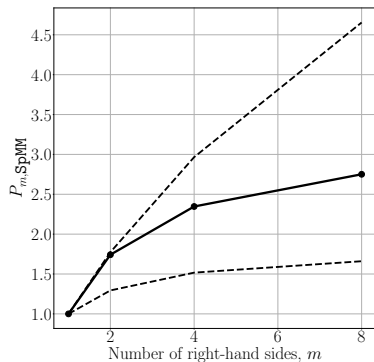


Numerical experiments

Turbulent planar channel flow: speed-up in the Poisson equation

Reminder

Using SP4 does not affect the definition of the Poisson equation



Conclusions

- High-order symmetry-preserving discretizations for collocated grids are presented.
- Its construction does not require addition operators to those of a second-order discretization.
- Higher-order discretizations lead to denser matrices.
- Additional costs of higher-order discretizations can be mitigated by exploiting repeated matrix-block structures.
- The diffusive operator obtains a 30% improvement in performance for $m = 8$ (compared to SP2).
- The convective operator obtains a 5% improvement in performance for $m = 8$ (compared to SP2).
- Repeated matrix-block structures can be exploited for the Poisson equation, with great speed-ups.

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