



Numerical Analysis of Parcel Tracking in Large Eddy Simulation of Polydispersed Multiphase Flows: Assessment of different Parcel Modeling Techniques

Linda Bahramian, F.Xavier Trias, Carles Oliet and C.David Pérez-Segarra

Heat and Mass Transfer Technological Center (CTTC), Universitat Politècnica de Catalunya – Barcelona Tech (UPC), ESEIAAT, Terrassa (Barcelona), Spain

Email: linda.bahramian@upc.edu

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Dispersed Two phase Flows:

- composed of a continuous phase and a dispersed phase in the form of unconnected particles or droplets.
- Using Eulerian-Lagrangian method (particle tracking)
- That is the best-suited for dispersed multiphase flows with thousands or millions of particles, and with a flow regime ranging from the very dilute up to relatively dense.
- to simulate the fuel injection of combustion chambers, cyclone separators, evaporative cooling, dispersion of pollutants, deposition of inhaled medicine in the human airways



a) Transient two-phase flow.





b) Separated two-phase flow.





c) Dispersed two-phase flow.

Using Parcels:

- In order to decrease the computational cost due to tracking each particles
- Each parcel represents the specified number of particles with the same properties
- two methods for arranging the particles in parcels: Number fixed method, NFM and Volume fixed method, VFM
- With increasing the volume for the VFM the results are not accurate for the smaller particles
- With increasing the Number of particles per parcel for NFM the results are not accurate for the bigger particles

The Objective:

- Implementing a new approach NFM-VFM which is a combination of NFM and VFM to enhance the particle behaviour regarding the limitation of the VFM and the NFM
- Analyzing the effect of the Stochastic subgrid model of Bini and Jones (BJ) on particle characteristics

Number of particles represented by a parcel: N_i Volume of a parcel: V_i









Dispersed phase:

Particle Equations of Motion:

for simplicity is assumed that the drag force is the only significant fluid-particle interaction force:

$$m_{\rm p}^{n} \frac{\mathrm{d}\mathbf{v}_{\rm p}^{\rm n}}{\mathrm{d}t} = m_{\rm p}^{n} \frac{\beta^{n} \left[\mathbf{u}(\mathbf{x}_{\rm p}^{\rm n}) - \mathbf{v}_{\rm p}^{\rm n}\right]}{\rho_{\rm p}} \qquad \beta^{n} = \frac{3}{4} \frac{C_{D} \rho}{d_{\rm p}} \left|\mathbf{u}(\mathbf{x}_{\rm p}^{\rm n}) - \mathbf{v}_{\rm p}^{\rm n}\right|$$

Continuous phase:

- Convective operator: Symmetry-preserving scheme \geq
- Pressure-velocity coupling: Fractional step method \geq
- Poisson equation: iterative Conjugate-Gradient (CG) method with Jacobi preconditioner \geq

Continuity equation:

$$\nabla \cdot \mathbf{u} = 0$$

Momentum equation:

$$\rho \left[\frac{\partial \mathbf{u}}{\partial t} + \nabla \cdot (\mathbf{u}\mathbf{u}) \right] + \nabla p = \mu \nabla^2 \mathbf{u} + S_u \qquad S_u = -\sum_{n=1}^{N_p} \frac{m_p^n \beta^n \left[\mathbf{u}(\mathbf{x}_p^n) - \mathbf{v}_p^n \right]}{\rho_p}$$

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Benchmark case:

- The confined jet of Hishida¹
- Particle-laden turbulent flow using one-way coupling approach by means of large eddy simulation (LES), using a synthetic turbulent generator for the inner jet
- > Particle mass flow rate in the inner jet = 5×10^{-3} , particle diameters= 64 µm, density= 2590 kg/m³



¹ Hishida, K. (1987), Turbulence characteristics of gas-solids two-phase confined jet (effect of particle density) Japanese Journal of Multiphase Flow, 1(1), pp. 56-69.

Validation:

Figure. Radial profiles of **fluid** mean velocity. Circle: Experiment; solid line: Numerical simulation. (a) x=0m; (b) x=0.065m; (c) x=0.13m; (d) x=0.26m



Figure. Radial profiles of **particle (dp=64µm**) mean streamwise velocity. Circle: Experiment; solid line: Numerical simulation. (a) x=0m; (b) x=0.065m; (c) x=0.13m; (d) x=0.2xm



Introduction

Designing new approach NFM-VFM:

- The particles with sizes above the Sauter mean diameter, SMD, are arranged with the VFM and the rest of them arranged with NFM
- Calculating the Sauter mean diameter in terms of a finite number of discrete size classes:
 p = 3 and q = 2





SMD

Introduction > Methodology >

Diameter distribution: 20 μm, 30 μm, 40 μm, 50 μm, 60 μm, 70 μm,

80 μm, 90 μm, 100 μm

 \checkmark

Sauter Mean Diameter = 60 µm

- By comparing the results of dispersed phase for the larger diameters by means of NFM
- $d_p = 60 \mu m$ d_p=70µm 30 30 25 25 W_p (m/s) 20 W_p (m/s) 20 15 no-parcel 15 NFM-5 10 no-parcel NFM-10 10 NFM-5 NFM-20 5 NFM-10 NFM-40 5 0 NFM-20 0.05 0.1 0.15 0.2 0.25 0.3 0 0 0.15 0.05 0.1 0.2 0.25 0.3 0 Streamwise distance z(m) Streamwise distance z(m) $d_p = 80 \mu m$ d_p=90µm 30 30 25 25 W_p (m/s) W_p (m/s) 20 20 15 15 10 no-parcel 10 NFM-5 5 5 no-parce NFM-10 NFM-5 0 0 0.05 0.15 0.2 0.1 0.25 0.3 0 0.05 0.1 0.15 0.2 0.25 0.3 0 Streamwise distance z(m) Streamwise distance z(m)





Methodology

Introduction

Test case

Conclusion

Np dp	5	10	20	40
60 µm	 Image: A second s	\checkmark	 Image: A second s	X
70 µm	 Image: A second s	 Image: A second s	X	X
80 µm	 Image: A second s	X	X	X
90 µm	X	X	X	X
100 µm	X	X	X	X

$$\begin{split} N_{p}\big|_{70} &= 20 \quad \rightarrow V_{p}\big|_{70} = N_{p}\big|_{70} \times \frac{4}{3}\pi \times \left(\frac{d_{p}}{2}\right)^{3} = 20 \times \frac{4}{3}\pi \times \left(\frac{70 \times 10^{-6}}{2}\right)^{3} \quad , \quad V_{p}\big|_{70} = V_{p}\big|_{60} \quad \rightarrow \quad N_{p}\big|_{60} = 31 \\ N_{p}\big|_{80} &= 10 \quad \rightarrow V_{p}\big|_{80} = N_{p}\big|_{80} \times \frac{4}{3}\pi \times \left(\frac{d_{p}}{2}\right)^{3} = 10 \times \frac{4}{3}\pi \times \left(\frac{80 \times 10^{-6}}{2}\right)^{3} \quad , \quad V_{p}\big|_{80} = V_{p}\big|_{60} \quad \rightarrow \quad N_{p}\big|_{60} = 23 \\ N_{p}\big|_{90} &= 5 \quad \rightarrow V_{p}\big|_{90} = N_{p}\big|_{90} \times \frac{4}{3}\pi \times \left(\frac{d_{p}}{2}\right)^{3} = 5 \times \frac{4}{3}\pi \times \left(\frac{90 \times 10^{-6}}{2}\right)^{3} \quad , \quad V_{p}\big|_{90} = V_{p}\big|_{60} \quad \rightarrow \quad N_{p}\big|_{60} = 16.8 \end{split}$$

dp	20µm	30µm	40µm	50µm	60µm	70µm	80µm	90µm	100µm
Parcel Type	NFM	NFM	NFM	NFM	NFM/VFM	VFM	VFM	VFM	VFM
Np	15	15	15	15	15	9	6	4	3

Comparing no-parcel, VFM, NFM-VFM:

In comparision with the no-parcel model, for the particles diameters below the SMD, the hybrid model shows better parcel dispersion and fewer discrepancies in the mean and the RMS velocity profiles of the dispersed phase than the VFM



Comparing no-parcel, NFM, NFM-VFM:

Observing the results of the no-parcel model, for the particle diameters above the SMD, this hybrid model presents better parcel dispersion and fewer discrepancies in the mean and the RMS velocity profiles of the dispersed phase than the NFM.



Particles subgrid Stokes number:

St =
$$\tau_p / T_{SGS}$$



- The values of the subgrid Stokes numbers of two different classes of particles (one small and one large particle class diameter) are above one in the majority of the streamwise direction.
- It leads to the conclusion that almost all particle classes can sense the majority of turbulence in the streamwise direction.

Stochastic Subgrid-Scales effect (Bini and Jones (BJ)):



Upon implementing the stochastic subgrid model of Bini and Jones (BJ), only minor differences are observed in the RMS velocities of the particles both in no-parcel and the hybrid model.

Conclusion:

- The hybrid model which was a combination of the NFM and the VFM was able to enhance the velocity profiles of the particles compared to the NFM and VFM for different range of particles.
- The effects of the Bini and Jones(BJ) stochastic subgrid model with this particle size distribution and density through this mesh configuration can be negligible on the RMS velocities of the dispersed phase in the streamwise direction.

Future work:

- Quantitative comparison of time-averaged distribution of particle dispersion, particle volume fraction and computational cost for different parcel models.
- Further in-depth analyses of the particle subgrid Stokes number, different stochastic subgrid models, and mesh sensibility will be required to draw more comprehensive conclusions for the stochastic subgrid effects on different particle characteristics.





Thanks For your attention!

Any question?

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